2.5 Constant potential vorticity flow from a wide basin: Gill’s model.

The Whitehead, Leetma and Knox (WLK) model discussed in the previous section was followed three years hence by a much more elaborate calculation due Gill (1977). In addition to his model, detailed below, Gill introducing a unifying framework for treating hydraulics problems. We have made repeated use of his formalism, particularly in the derivation of conditions for hydraulic criticality. This material was reviewed and generalized in Section 1.5. The model developed by Gill was based on his particular view of the upstream basin and is rather more involved than that of WLK. Some investigators are have found Gill’s scaling and choice of upstream parameters unintuitive and have developed their own versions of his basic model. In consideration of the historical importance of Gill’s paper, our preference in presenting the work is to first describe the model as originally formulated. The next section will discuss some insights that are gained from alternative formulations.

(a) Basics

The depth and velocity profiles predicted by zero potential vorticity models such as WLK are valid near the sill, where the local depth (scaled by $D$) is small compared to the reservoir depth $D_\infty$. However, these expression do not apply in the reservoir, where by hypothesis the depth equals $D_\infty$. We are therefore unable to verify the self consistency of the model, in particular the hypothesis that a quiescent, infinitely deep upstream state can be linked to the sill flow in a dynamically consistent way. In thinking about the character of the upstream flow, one might also wish to consider other possible states. Observations from deep straits such as the Faroe Bank Channel suggest the bulk of the overflow comes from intermediate water masses, which span the relatively wide upstream basin but may not be significantly thicker than the layer depth at the sill. Some or all of these considerations led Gill (1977) to consider non-zero (but still uniform) values of $q(= D / D_\infty)$. The depth and velocity profiles across the channel are now given by the more general forms (2.3.1) and (2.3.2), which admit the possibility of boundary layers. In the WLK model the boundary layer thickness is much larger than the channel width. Most of the novel features of Gill’s model can be linked to the presence boundary layers that are as thin or thinner than the channel width.

We continue to employ rectangular cross-sectional geometry and we analyze the case of non-separated flow first. The steady forms of (2.2.15) and (2.2.16) then require conservation of the volume transport $Q$ and the average $\bar{B}$ of the Bernoulli function on the two walls. Since we no longer care about special values or limits of $D$ (such as $D<<D_\infty$) we are free to set it to any convenient value. The choice $D= (fQ^* / 2g)^{1/2}$ is convenient as it is equivalent to setting $Q=2$ (see Exercise 1) in the statement of conservation of mass (2.2.18). Therefore

$$\bar{d}\hat{d} = 1. \quad (2.5.1)$$
In addition, conservation of the energy (2.2.16 and 2.2.17) for the steady flow implies

\[
\frac{1}{2} q [T^{-2} \hat{d}^2 + T^{-2} (\hat{d} - q^{-1})^2] + \hat{d} + h = \bar{B}, \tag{2.5.2}
\]

where again \( T = \tanh\left(\frac{1}{2} q^{1/2} w\right) \) and \( \bar{B} \) is the average of the side-wall values of the Bernoulli function. Eliminating \( \hat{d} \) from these two equations gives

\[
T^2 (\hat{d} - q^{-1})^2 + \frac{1}{T^2 \hat{d}^2} + 2q^{-1}(\hat{d} + h) = 2q^{-1} \bar{B}, \tag{2.5.3}
\]

The parameter \( \bar{B} \) is generally not a convenient nor intuitive measure of the reservoir state. As discussed in Section 2.2, a flow in reservoir much wider than \( L_d \) will be contained in side-wall boundary layers of thickness \( L_d \) (Figure 2.5.1). The physical separation of the boundary layers makes it difficult to see how \( \bar{B} \) would be specified in a laboratory experiment or oceanic setting. Furthermore, the velocity along each wall is generally non-zero and the Bernoulli functions there may no longer be dominated by the potential energy terms \( h+d \), as assumed in the WLK model. Only in the interior of the reservoir, at a distance \( \gg L_d \) from either wall, will the velocity be small. There the dimensional depth is \( D_\infty \) (or \( d=q^{-1} \)) according to (2.2.12). With these ideas in mind, Gill (1977) suggested that a new parameter measuring the partitioning of the total transports in the boundary layers would be more descriptive than \( \bar{B} \). Some other choices be discussed in the next section.

Let the transport streamfunction \( \psi \) have the value \( \pm 1 \) on the side walls \( x=\pm w/2 \), so that the total transport is 2, as assumed. Further, let \( \psi_i \) denote the value of \( \psi \) in the quiescent interior separating the two upstream boundary currents. The transports in the right- and left-hand boundary currents (facing downstream) are therefore \( 1-\psi_i \) and \( 1+\psi_i \). Included is the possibility that \( |\psi_i| > 1 \) in which case one of the boundary layer transports will be greater than 2 and the other will be negative. Also note that the dimensionless value of \( d \) in the reservoir interior is \( q^{-1} \). We can write \( \psi_i \) in terms of \( \bar{B} \) by first integrating \( dB / d\psi = q \), yielding \( B = \bar{B} + q\psi \). Then note that \( B (=\frac{1}{2}v^2 + d + h) \) has value \( q^{-1} \) along \( \psi=\psi_i \), as follows from evaluating \( B \) in the quiescent region where \( v=0, \ d=q^{-1}, \) and where we will take \( h \) to be zero. Thus

\[
\bar{B} = q^{-1} - q\psi_i, \tag{2.5.4}
\]

and substitution into (2.5.3) results in

\[
G(\tilde{d};T,h) = T^2 (\tilde{d} - q^{-1})^2 + \frac{1}{T^2 \tilde{d}^2} + 2q^{-1}(\tilde{d} + h) - 2(q^{-2} - \psi_i) = 0 \tag{2.5.5}
\]
This function $G(\tilde{d}; T, h)$ is of the form sought by Gill (1977) and (2.5.5) may be solved giving $\tilde{d}$ for the local values of $T(w(y))$ and $h(y)$. The parameters describing the upstream flow are $\psi_i$ and the interior reservoir depth $q^1$. In light of the particular choice of $D$ this last parameter can also be written as $(2gD_c^2 / fQ^* )^{1/2}$ leading to an alternative interpretation; for a fixed interior depth $D_c$ the maximum possible geostrophic transport in the left-wall boundary layer occurs when the depth along the left wall is zero. This transport is given by $Q_{\text{max}} = gD_c^2 / 2f$ and therefore $q = 2(Q^*/Q_{\text{max}})^{1/2}$. In summary, it is possible to think about the reservoir parameters entirely in terms of volume transports, $\psi_i$ governing the partitioning between boundary layers and $q$ governing the total transport relative to the maximum possible value in the left-hand boundary layer.

(b) Critical states.

Critical states are found by taking $\partial G / \partial \tilde{d} = 0$, resulting in

$$(1 - T_c^2)q^{-1} + T_c^2 \tilde{d} = \tilde{d}^{-3/2}, \quad (2.5.6)$$

where the subscript ‘$c$’ denotes quantities evaluated at a critical section. The reader may recall the expression for the characteristic speed $c_-$ of a Kelvin wave propagating along the left-hand ($y=w/2$) wall:

$$c_- = q^{1/2}T^{-1}\tilde{d} - \tilde{d}^{1/2}[1 - T^2(1 - q\tilde{d})]^{1/2} = 0$$

(cf.2.2.22) and it is simple to show that $c_- = 0$ is equivalent to (2.5.6). Gill (1977) also defined a Froude number

$$F_d = \frac{q^{1/2}T^{-1}\tilde{d}}{d^{1/2}[1 - T^2(1 - q\tilde{d})]^{1/2}} = \frac{\sqrt{v}}{d^{1/2}[1 - T^2(1 - q\tilde{d})]^{1/2}} \quad (2.5.7)$$

such that $F_d (<1,=1,>1)$ indicates (subcritical, critical, and supercritical) flow corresponding to $c_-$ ($<0,=0,>0$). As pointed out in Section 2.2, this Froude number should not be interpreted as the ratio of an advection to relative propagation speed. However it does measure the ability of a Kelvin wave, trapped to the left wall of the channel, to propagate upstream. If $F=1$ this wave is stationary; if $F>1$ it propagates downstream.

The geometric requirements for critical flow are obtained by setting $dG / dy = 0$ in (2.5.5). If the channel width is constant, critical flow can only occur where $dh / dy = 0$ as before. When $h$ is constant the requirement becomes
\[ [T_c^4 (\bar{d} - q^{-1})^2 - \bar{d}^{-2}] dw / dy = 0 , \quad (2.5.8) \]

implying that \( dw / dy = 0 \), as at a contraction, or that the coefficient in brackets is zero. As in the WLK model, it can be shown that the latter implies that \( v_c (w / 2, y) = 0 \), (see Exercise 2). Thus critical flow can occur away from the contraction if the flow separates from the left wall and the right wall \( v \) is zero.

We now turn to the case of separated flow. Here \( \hat{d} = \bar{d} = 1 \) in view of (2.5.1) and the only dependent variable is the width parameter \( T_e = \tanh(q^{1/2} w_e / 2) \), where \( w_e \) is the separated stream width. As shown by (2.3.7) and (2.3.8), the equations relating the flow to the geometry are identical to those describing non-separated flow, but with \( T \) replaced by \( T_e \). With this replacement and with \( \hat{d} = 1 \), (2.5.5) leads to an altered hydraulic function:

\[ G(T_e; h) = T_e^2 (1 - q^{-1})^2 + \frac{1}{T_e^2} + 2q^{-1} (1 + h) - 2(q^{-2} - \psi_f) = 0 . \quad (2.5.9) \]

The channel width \( w(y) \) does not enter this relation and thus the separated current width responds only to changes in bottom elevation \( h \). If \( h \) remains constant, changes in the position of the right wall lead to identical changes in the position of the left edge of the separated flow. This property clarifies the condition implied by the vanishing of the bracketed term in (2.5.8). Along a horizontal bottom, critical separation of the flow can occur where \( dw/dy \) is non-zero since the actual width \( w_e \) of the flow becomes stationary \( dw_e/dy = 0 \) at that point.

The conditions for critical flow are obtained by setting \( \partial G / \partial T_e = 0 \) with \( G \) defined by (2.5.9) and this leads to

\[ q^{-1} = 1 + T_e^{-2} \quad (2.5.10) \]

Since \( T_e \) must be \(< T_c \) for the critical flow to be separated, (2.5.10) requires

\[ q^{-1} \geq 1 + T_e^{-2} . \quad (2.5.11) \]

It can also be shown that separated critical flow has \( v = 0 \) on the right wall (see Exercise 2), a property that could have been anticipated on the basis of remarks surrounding Figure 2.9.

It can also be shown that the long wave speeds in this case are given by

\[ c_\pm = q^{1/2} T_e^{-1} \pm [1 - T_e^2 (1 - q)]^{1/2} = 0 , \]
which is just the expression for attached flow (cf 2.2.22) but with \( \hat{d} = \bar{d} = 1 \) and \( T \) replaced by \( T_e \). The corresponding Froude number is

\[
F = T_e^{-1} \left[ \left( 1 - T_e^2 \right) q^{-1} + T_e^2 \right]^{-1/2} .
\]  

(2.5.12)

(c) Steady Flows

Before discussing actual solutions it is worth noting several results regarding flow separations and reversals. First, if the fluid depth in the reservoir is nonzero across the reservoir width, then the current downstream will remain in one continuous band across each section of channel. The depth may go to zero at the left wall and the current may separate there, but the current may not split into multiple branches. This follows from the theorem described in connection with Figure 2.2. In addition, the along channel velocity may reverse signs only once in the interior of the flow (see Exercise 1 of Section 2.2). Finally, \( v \) must remain non-negative at a critical section and the proof of this is discussed in Exercise 3.

Trying to develop a detailed understanding of Gill’s model over all parametric variations and channel geometries is nearly impossible. Instead we will attempt to illustrate the features of the solutions that are interesting and exhibit behavior different from that of the WLK model. To begin with, consider the behavior of the solutions when the channel bottom is horizontal and the flow is forced only by width contractions. Figure 2.5.2 shows plots of the solution curves (\( \bar{d} \) as a function of \( T \)) for various values of the interior reservoir depth \( q^{-1} \). All curves have \( \psi_i = 1 \) so that the reservoir is drained entirely by the left-hand boundary layer with no transport in the right-wall layer. Such an upstream state is often imagined to occur if the flow is started from rest as the result of the breakage of a barrier located in the channel. The breakage would excite a Kelvin wave that would move into the reservoir along the left wall and set up the draining flow. (There are a number of complicating factors that arise in such experiments. For example a finite reservoir would allow the Kelvin wave to propagate around the perimeter and reenter the channel. However, the draining flow along the left wall would at least persist for some finite time.)

The solution space of Figure 2.5.2 has been restricted to \( \bar{d} \geq 1 \) (non-separated flows) since changes in the properties of separated flows can only be forced by bottom topography. The curves \( q^{-1} = \text{const.} \) can be used to construct particular solutions for different upstream states. To determine the appropriate value of

\[
q^{-1} = 2 \left( Q_{\text{max}}^* / Q^* \right)^{1/2} = 2 \left( g D_\infty^* / 2 f Q^* \right)^{1/2}
\]

one would need to select the flow rate \( Q^* \) and the interior reservoir depth \( D_\infty \) in order to determine the appropriate curve. The values of \( \bar{d} \) for a range of channel widths could be traced out by following this curve. Note that all the curves extend between the right edge
(T=1) of the diagram, corresponding to the reservoir (w→∞), and the lower boundary d = 1, corresponding to a point of separation. Since the slope of the curves near the lower boundary is negative, w is increasing as the separation point is approached. If further increases in width occur downstream of that point the stream will separate and continue at the same width with no further changes in properties. Each solution has a supercritical branch and a subcritical branch that merge at a point determined by the critical condition (2.5.6), indicated by the dashed line. Note that this line lies above d = 1, indicating that all separated flows are supercritical for ψi=1.

Once a particular q^{-1} is selected, it is natural to follow the solution by beginning in the reservoir (T=1) and tracing along the appropriate curve in Figure 2.5.2 until the narrowest section of the channel is reached. (Two of the reservoir states are drawn in the figure insets at the right.) If the narrowest section is reached before the dashed line is encountered, the solution is subcritical with no hydraulic transition. Downstream of the narrows, the solution is obtained by retracing the solution curve back towards T=1 as the channel widens. All such solutions are non-separated. If T at the narrows happens to be the critical Tc, then the dashed curve is crossed there and the downstream flow is supercritical. All supercritical branches of the solution curve terminate on the line d = 1 indicating flow separation for sufficiently large w. If the narrows is sufficiently constricted that T < Tc for that curve, then a complete steady solution cannot be constructed. In this case a time-dependent adjustment must occur, perhaps resulting in a change in q, ψi, or both. Figure 2.5.2 suggests that, in the absence of changes in ψi the upstream depth must increase to accommodate the narrower width.

A limiting case is q=2 corresponding to separation of the reservoir flow from the left wall. Here the outflow transport is the maximum that can be carried by the left boundary layer (q^*=Q^*_max). Higher transports are possible in general, but these require flow in the right boundary layer. When the flow in the reservoir is separated it is also critical, as suggest by the figure or by (2.2.26). Downstream of the reservoir, the channel would have to remain infinitely wide to sustain a solution.

Next consider the opposite case of variable topography with constant width. Since we have already assumed the reservoir to be infinitely wide, it is convenient to imagine the reservoir narrowing to a finite value, during which h remains zero, followed by a constant-width section containing a sill. Figure 2.5.2 is used to track the solution over the variable section of channel and Figure 2.5.3, which shows solution curves for variable h and fixed width (w^*/Ld=.75 or T=.63), is then used to continue further. The solution space of Figure 2.5.3 is divided into two regions: the upper portion (d > 1), for which the flow is non-separated and the dependent variable is d, and the lower portion (d < 1), for which the flow is separated and Te is the dependent variable. As before, ψi=1 and critical flow is marked by a dashed line.

If one begins at the upstream end of the uniform width section, where h=0 and where the flow is subcritical, the solution lies along the upper left hand border of Figure 2.5.3. Increases in h cause d to decrease as one follows the appropriate q^{-1}=constant
very rough draft-not for distribution

curve. There are now two scenarios depending on the value of the interior reservoir depth. If \( q^{-1} < 3.5 \) the flow will become critical before separation point \( \vec{d} = 1 \) is reached, so that separation will occur downstream of the sill. This behavior occurs for relatively low sills (\( h_m < 1.5 \)). If \( D_\infty / D > 3.5 \) the flow separates upstream of the sill (while it is still subcritical) and remains subcritical until it reaches the sill, where it becomes critical. Here both the interior reservoir surface elevation and the sill elevation are relatively high.

(d) Transport relations.

The essential nature of upstream influence in a hydraulic model is expressed as a relationship between the parameters that characterized the basin flow and the control section geometry. In the nonrotating models discussed earlier, and in the WLK model, this relationship takes the form of a ‘weir formula’ in which the volume transport \( Q^* \) is written in terms of the basin surface elevation \( \Delta z^* \) above the sill. The situation in the Gill model is more complicated; for one thing the surface elevation varies across the upstream basin. The weir relationship is most easily expressed for the case of separated flow at the critical section. If (2.5.9) is applied there and (2.5.10) is used to eliminate \( T_{ec} \) from the resulting equation, one obtains

\[
h_c = q^{-1} - 2 - (1 - \psi_i)q
\]  

(2.5.13)

Because of Gill’s choice of the scaling factor \( D = (fQ^*/2g)^{1/2} \), the volume flux is hidden in the nondimensionalization. An explicit formula for \( Q^* \) follows from the dimensional equivalent

\[
\left( \frac{fQ^*}{2g} \right)^{1/2} = D_\infty - \left( D_\infty h_c^* + \frac{f\psi_i^*}{g} \right)^{1/2}
\]  

(2.5.14)

(see Exercise 4.) In contrast to the nonrotating case and the zero potential vorticity case, two measurements in the reservoir are now necessary in order to compute the volume flux \( Q^* \). A depth measurement in the reservoir interior gives \( D_\infty \) while a depth measurement along either wall and use of the geostrophic relation gives \( \psi_i^* \). Of course, depth measurements on both sidewalls would give the geostrophic transport directly and thus the utility of (2.5.14) is called into question. An alternative is discussed in the next chapter.

For non-separated flow the situation is more difficult. Applying (2.5.6) at the critical section, adding \( \vec{d}_c \) times (2.5.5), and multiplying the result by \( q / 2 \) gives

\[
h_c = (1 - \frac{1}{2}T_c^2)q^{-1} - \frac{3}{2}(1 - T_c^2)\vec{d}_c - (\psi_i + T_c^2\vec{d}_c^2)q
\]  

(2.5.15)

or dimensionally:
\[ h_c^* = (1 - \frac{1}{2} T_c^2) D_w + \frac{1}{2} (T_c^2 - 1) \bar{d}_c^* - D_w(2 \bar{T}_c^* \bar{d}_c^* + \psi_i^* f / g) \]  

(2.5.16)

In addition, the dimensional version of (2.5.6) is

\[ (1 - T_c^2) D_w \bar{d}_c^* + T_c^2 \bar{T}_c^2 = \frac{f^2 Q^* t^2}{4 g^2 \bar{d}_c^* T_c^2} \]  

(2.5.17)

If the algebraic complexity was not prohibitive, a ‘weir’ relation could be obtained by eliminating \( \bar{d}_c^* \) between the last two equations. In general, the relationship between \( Q^* \), \( D_w \) and \( \psi_i^* \) for a given \( h_c^* \) must be determined numerically. This subject is pursued further in Section 2.6, where different choices of scales and of the upstream parameters lead to more elegant formulations.

(e) Limiting Cases

One of the most instructive limiting cases is that of a uniform and wide channel (\( w \rightarrow \infty, \ T \rightarrow 1 \)) with bottom topography. Most of the novel features of the full problem are present in this setting. Critical flow must occur at the sill and we first examine the case in which the sill flow is separated. The nondimensional relationship between the sill height and the upstream variables is given by (2.5.13). In addition (2.5.11) requires that \( q^{-1} \geq 2 \) with marginal separation occurring at \( q^{-1}=2 \). In this regime it is also possible for the upstream flow to be separated and the value of \( h_c^* \) at marginal separation can be calculated by evaluating (2.5.9) in the reservoir (\( h=0 \)) and setting \( T_e=1 \). If (2.5.13) is then used to eliminate \( \psi_i^* \) from the resulting relation, one finds

\[ h_c^* = \frac{3 + (1 - q^{-1})^2}{2q^{-1}} - 1 \]  

(2.5.18)

The case of attached flow is more subtle. In Section 2.2 we showed that the characteristic speed of a left wall Kelvin wave for \( T=1 \) is proportional to the negative of the depth at the left wall (see 2.2.26). The flow must therefore be subcritical if the flow is attached at the left wall, a finding that rules out critical control of attached flow in the problem under consideration. However, if we consider a channel of large but finite width then a class of attached, critically controlled flows arises. These solutions are described by expanding (2.5.6) and (2.5.15) in powers of \( 1 - T_c^2 \). The former becomes

\[ \bar{d}_c^* = 1 + \frac{1}{2} (1 - T_c^2)(2 - q^{-1}) + O[(1 - T_c^2)^2] \]  

(2.5.19)

showing that marginal separation (\( \bar{d}_c^* \rightarrow 1 \)) occurs as \( 1 - T_c^2 \rightarrow 0 \) as anticipated. However, the first correction to this limit allows the possibility of attached flows \( \bar{d}_c^* > 1 \) provided
that $q^{-1}<2$. These flows are close to separation at the critical section and the relationship between the upstream variables and $h_c$ is given by the expansion of (2.5.15):

$$h_c = \frac{1}{2} q^{-1} - q(1 + \psi_i) + O(1 - T_c^2). \quad (2.5.20)$$

Figure 2.5.4 shows the solutions to either (2.5.13) or (2.5.20) with $\psi_i$ plotted as a function of $h_c$ and $q^{-1}$. Each point in the diagram represents a specific, hydraulically controlled flow. The reader should bear in mind the definitions of the governing parameter in terms of dimensional quantities:

$$h_c = \frac{h_c^*}{(f Q^*/2g)^{1/2}}, \quad q^{-1} = \left(\frac{2g D^2}{f Q^*}\right)^{1/2}, \quad \text{and} \quad \psi_i = \frac{2\psi_i^*}{Q^*} \quad (2.5.21)$$

As before, the presence of $Q^*$ in the scaling make it difficult to calculate the flux using the figure. However, it is quite interesting to explore the various steady regimes. In the upper part of the figure ($q^{-1}>2$) the flow is separated at the critical section, here a sill. Since the effective width $w_{ec}$ of the separated flow is determined completely by $q^{-1}$, these widths have been indicated along the right-hand border of the figure. The dashed curve is determined by (2.5.18) and the region lying to left corresponds to flows that are also separated in the upstream basin, so that no contact with the left wall is made along the entire length of channel. All such solutions have $\psi_i>1$, implying that the approach flow in the reservoir is along the left-hand free edge and that some of this flow returns upstream along the right wall before reaching the sill, as shown in Inset A. Such a solution could be considered a coastal flow forced by along-shore changes in topography. To the immediate right of the dashed region the upstream flow is non-separated but the flow at the sill is separated. In addition the approach flow is concentrated in the left-hand boundary layer, as sketched in Inset B. Continuing to move to the right into regions of higher sill elevation, one enters a region where $-1 \leq \psi_i \leq 1$, so that the approach flow is unidirectional, as shown in Inset C. One of the interesting aspects of cases A, B, and C is that the critical width $w_{ec}$ is often $O(1)$ or less. Thus, approach flow along the left-hand edge can cross the channel and be carried close to the right hand boundary at the sill. The remaining region in the upper part of Figure 2.5.4 ($\psi_i<1$) corresponds to approach flow along the right hand wall with some return flow along the left-hand wall, as sketched in Inset D.

In the lower part ($q^{-1}<2$) of Figure 2.5.4 the flow is marginally attached at the sill. Since $\psi_i \leq 1$ in this lower region, the upstream flows are either unidirectional or approach along the right-hand wall and partially return along the left-hand wall, as sketched in Insets E and F. One of the interesting characteristics of the type F flows is that the surface or interface elevation in the interior of the reservoir can be lower than the sill elevation ($D_\infty < h_c$). (This can be shown by holding $q^{-1}(= D_\infty / D)$ constant in (2.5.19) and taking $\psi_i$ sufficiently negative and large.) Of course, only the interior interface elevation is below the sill (the elevation along the right-hand wall remains above the sill). It is also natural to inquire after the dynamics that allow the upstream flow to cross from
the right to the left side of the channel before the sill is reached. What happens, in fact, is that a weak along-channel pressure gradient exists in the interior, supporting a cross-channel geostrophic flow. Since $d = q^{-1}$ and $v \equiv 0$ in the channel interior, the $y$-momentum equation reduces to

$$u \equiv -\frac{\partial h}{\partial y}.$$ 

On the upstream face of the obstacle $\partial h / \partial y > 0$, a negative (right-to-left) geostrophic flow exists, whereas the opposite situation occurs on the downstream face.

A second limit to consider is that of small potential vorticity ($q<<1$). Since $q = (fQ^*/2gD_e^3)^{1/2}$ this limit can be achieved by fixing $Q^*$ and increasing $D_e$. The critical condition for attached flow (2.5.6) requires that

$$\bar{d}_c = (\frac{1}{2}w_c)^{-2/3} + O(q)$$

while (2.5.15) gives

$$h_c = q^{-1} - \frac{1}{2}(\frac{1}{2}w_c)^2 - \frac{1}{2}(\frac{1}{2}w_c)^{-2/3} + O(q). \tag{2.5.22}$$

provided $\psi_i$ remains fixed. To lowest order, the sill height must increase in proportion to the interior reservoir depth $q^{-1}$ (dimensionally $D_e$). As $D_e$ increases, the width $\sqrt{gD_e}/f$ of the boundary layers also increases and the flow penetrates further into the interior. At the same time, the difference in depth across the boundary layers decreases in order to preserve the boundary layer transports (proportional to the difference in the square of the depths). As the bounding interface flattens the velocities in the reservoir decrease and the upstream flow approaches the quiescent state hypothesized in the WLK model. In fact, it can be shown that dimensionalization of (2.5.22) leads to the WLK transport formula (2.4.10) for attached flow. A similar result follows for the case of separated flow.

The Gill model is rather difficult to digest and it is worth recapping some of the highlights. These include introduction of the concept of potential depth $D_e$ and the appearance of a global deformation radius $L_d = (gD_e)^{1/2}/f$ which is uniform throughout the fluid regardless of the local depth. Another novel feature is the containment of the flow in boundary layers of thickness $L_d$. Exploitation of this structure in the wide upstream reservoir allows one to use $\psi_i$ as a parameter in place of the less intuitive $B$. Critical control of the flow is exercised by Kelvin waves or their frontal counterparts, both of which are trapped to side walls or free edges. Another new feature of Gill’s model is that three dimensional parameters ($Q^*, D_e$, and $\psi_i^*$) are needed to specify the upstream state. If the flow is hydraulically controlled, so that $Q^*$ is a function of $D_e$ and $\psi_i^*$, then just the
latter two are needed. Thus, a ‘weir’ formula relating $Q^*$ to a single upstream depth is not possible without further approximation. Finally, some of Gill’s solutions exhibit interesting new behavior including counterflows, crossing of the fluid from one side of the channel to the other over great distances, and instances in which the interior reservoir interface level lies below the sill level.

Comments:

: Equation (2.5.5) is the same as Gill’s (5.13) if I set $Q=2$ and thus have $\psi = \pm 1$ at the walls. His equation has $4\psi$ rather than $2\psi$ on the r.h.s. but this is because he has $\psi = \pm 1/2$ on the walls. In interpreting his figures, his $\psi_i=1/2$ is our $\psi_i=1$.)

No real experimental or numerical verification of the Gill theory has, to my knowledge, been made. (The experiments of Shen 1981 and WLK are more applicable for $q=0$.) One of the problems is a lack of satisfactory numerical algorithms.

Exercises

1) Show that setting $D = (fQ^*/2g)^{1/2}$ is equivalent to setting $Q=2$.

2) In connection with (2.5.8) show that $[T_c^4(d_c^2 - q^{-1})^2 - d_c^{-2}] = 0$ implies that $v_c(w/2, y) = d_c(-w/2, y) = 0$.

3) By following the steps outlined below, show that non-separated flow at a critical section must be unidirectional in $-w/2 < y < w/2$ provided that the (uniform) potential vorticity is non-negative. Further show that separated critical flow must have $v(w/2, y) = 0$.

   (a) Use the result of Problem 1 of Section 2.2 to argue that the flow is unidirectional at any $y$ provided that $v(y, w/2)$ and $v(y, -w/2)$ do not differ in sign.

   (b) Introduce the quantity $r = \hat{v} / \bar{v}$ and argue that the flow is unidirectional for $|r| < 1$ and has $v(y, w/2) = 0$ for $r = -1$. Further show that $r = T^2 \tilde{d}(d_c - q^{-1})$

   (c) Using the critical condition (2.5.6) along with (2.5.1), show that

   $$ r = \frac{T_c^2 d_c^2 - d_c^{-2}}{1 - T_c^2} $$

   and deduce that $r = -1$ when the flow is separated from the left wall ($\tilde{d}_c = 1$).

   (d) For attached flow ($\tilde{d}_c > 1$) show that $r > -1$. Then show that the requirement of non-negative potential vorticity and the result of (c) lead to $r \leq 1$. 
4. Through dimensionalization of (2.5.13) show that

\[
\left( \frac{fQ^*}{2g} \right)^{1/2} = D_n \pm \left( D_n h_c^* + \frac{f \psi_i^*}{g} \right)^{1/2}.
\]

Next, show that only the ‘-‘ sign is appropriate. (Hint: one way to do this is to consider the case of an infinitely wide channel and with no flux in the right-wall boundary layer.)

**Figure Captions**

2.5.1 Gill’s (1977) ideal of the upstream basin or reservoir.

2.5.2 Solution curves for flow through a pure contraction. Note that \( T = \tanh(q^{1/2}w / 2) \).

2.5.3 Solution curves for flow over a sill in a constant width channel. The lower half of the diagram applies to separated flow, with \( T_c = \tanh(q^{1/2}w_c / 2) \).

2.5.4 Regime diagram showing various states of separation and recirculation for flow in an infinitely wide channel with a sill. The definition of the parameters is given in (2.5.21). Solutions to the left of the dashed line are entirely separated from the left wall. Those lying below the line \( q^{1/2} = 2 \) are attached at and upstream of the sill.
\( d^* = D \) (or \( d = q^{-1} \))
and \( \psi^* = \psi_i^* \)

Figure 2.5.1
Figure 2.5.2

\[ T = \tanh\left(\frac{q^{1/2}w}{2}\right) \]

\[ q^{-1}(=D/D_\infty) = 4 \]

\[ q^{-1} = 3 \]

\[ q^{-1} = 2.1 \]

\[ q^{-1} = 0 \]

D_\infty

\( \bar{d} \)

\( T \)

supercritical

subcritical
Figure 2.5.3
Figure 2.5.4