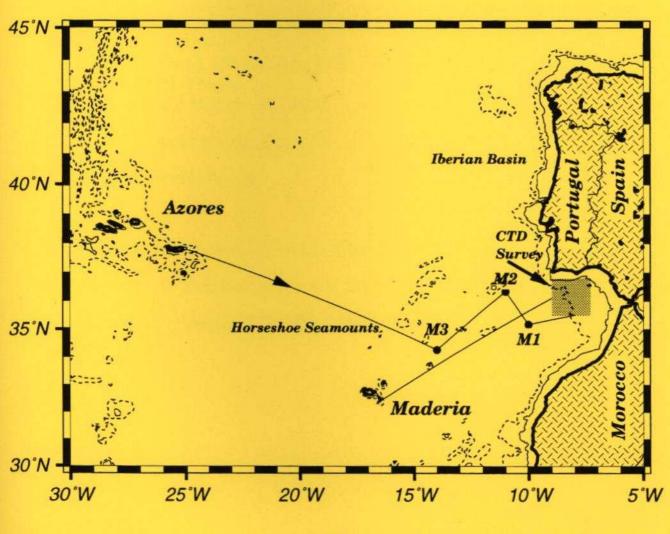
A Mediterranean Undercurrent Seeding Experiment (AMUSE):

Part I: Program Description and Hydrographic Measurements

by

Amy S. Bower, Julie Pallant, and Cynthia L. Chandler

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Woods Hole Oceanographic Institution Woods Hole MA 02543

Table of Contents

List of Figures	ii
List of Tables	ii
List of Cruise Participants	ii
Abstract	iv
Section 1: Introduction	1 1 1
Section 2: Methods	9 9 10 13
Section 3: Acknowledgements	14
Section 4: References	14
Appendix A: Vertical Profile Plot Series	A-1
Appendix B: Temperature vs. Salinity Plot Series	B-1
Appendix C: Vertical Section Plot Series	C-1

List of Figures

Cover Figu	are. Chart showing cruise track	
Figure 1.	Chart showing cruise track	3
Figure 2.	Chart showing CTD station locations	4
Figure 3.	Chart showing RAFOS float track - AM101	11
	RAFOS Float AM101 Temperature and Pressure records.	

List of Tables

			
Table 2.	RAFOS Float information	***************************************	10
Table 3.	Sound source information		13

List of Cruise Participants

Woods Hole Oceanographic Institution

Dr. Amy S. Bower (Chief Scientist)

Mr. John N. Kemp

Mr. James R. Valdes

Scripps Institution of Oceanography

Dr. Laurence Armi Mr. Vitalii Sheremet

University of Rhode Island

Mr. Jan J. Szelag

University of Lisbon

Mr. Joaquim G. H. Dias Ms. Anabela T. L. Simoes Ms. Fatima M. M. Sousa

Abstract

A Mediterranean Undercurrent Seeding Experiment (AMUSE) was undertaken to study the dispersion of Mediterranean Water into the North Atlantic via Mediterranean Water eddies (meddies) and other processes. The major field effort in AMUSE was the sequential deployment of acoustically-tracked, subsurface RAFOS floats in the Mediterranean Undercurrent south of Portugal between May 1993 and March 1994. The float deployments were accompanied by XBT sections across the Undercurrent. Before the float deployments, a detailed Conductivity-Temperature-Depth (CTD) survey of the Undercurrent was carried out to determine the best launch site for the RAFOS floats. Three acoustic sound source moorings (for tracking the floats) and two test floats were also deployed during the CTD cruise. This report represents Part 1: A basic description of the AMUSE program and the presentation of the 113 CTD stations from the hydrographic survey. Part 2 contains a summary and graphical presentation of the RAFOS float data collected during AMUSE.

Section 1: Introduction

A. Description of Scientific Program

"A Mediterranean Undercurrent Seeding Experiment" (AMUSE) was conducted to study the dispersion of Mediterranean Water into the North Atlantic. The Mediterranean Outflow represents a significant source of heat and salt to the North Atlantic Ocean, but the pathways by which the Outflow water spreads into the North Atlantic are not well-known. After the Outflow water exits the Mediterranean through the Strait of Gibraltar, it generally follows the continental slope south of Spain and Portugal in a coherent subsurface jet known as the Mediterranean Undercurrent. Along this path, the Outflow water sinks and entrains a significant amount of Atlantic water.

The goal of AMUSE was to determine where and how the Outflow water in the Undercurrent leaves the continental slope and enters the deep eastern North Atlantic. A significant fraction of the Outflow water enters the North Atlantic in small, subsurface eddies called Meddies, and a specific focus of AMUSE was to determine where and how often Meddies form.

The major field effort in AMUSE consisted of a sequential deployment of acoustically-tracked, subsurface RAFOS floats (Rossby, et al., 1986) in the Mediterranean Undercurrent south of Portugal, accompanied by Expendable Bathythermograph (XBT) observations across the Undercurrent. Before the float deployment began in July, 1993, a detailed Conductivity-Temperature-Depth (CTD) survey of the Undercurrent was conducted to determine the best launch site for the RAFOS floats. Three acoustic sound sources and two RAFOS floats were also deployed during the CTD survey to test the acoustic tracking system. This report contains a summary of the observations made during this CTD survey which was carried out on R/V OCEANUS in April-May, 1993. The results from the sequential float deployments will be presented in a later report.

B. Cruise Narrative

The R/V OCEANUS left Ponta del Gada, Azores on schedule on 30 April 1993 with 8 scientific personnel on board. The first sound source mooring (M3) was deployed on 2 May, mooring M2 on 3 May and M1 on 4 May (see Figure 1 for cruise track). The ship then steamed to the Gulf of Cadiz south of Portugal and began a detailed CTD survey of the Mediterranean Undercurrent on 4 May. The survey covered the area 35° 30' N to 36° 45' N and 7° 30' W to 9° 00' W. A total of 113 CTD stations were made with cast depths ranging from 500 to 2000 meters. Casts extended to within about 10 meters of the bottom or to 2000 meters (see Table 1 and Figure 2).

On 6 May a personnel transfer took place outside Faro Harbor in Portugal. The two mooring technicians on board disembarked and one Portuguese scientist embarked. The transfer was accomplished with the help of the Portuguese Navy. It was expected that two Portuguese scientists would board at Faro, but due to a family emergency, the second scientist was unable to join the cruise. On 11 May the CTD survey was completed and two RAFOS floats were launched at CTD stations 110 and 111.

At several times during the cruise, sonobuoys were deployed to listen for the sound sources. This turned out to be a very successful operation. All three sources deployed during the cruise were heard, and an additional source, deployed by German scientists in the same vicinity, was also heard.

Much of the CTD survey took place in the shipping lanes between Cape St. Vincent and the Strait of Gibraltar. In addition, NATO military exercises were being conducted in this region. In spite of significant ship traffic, the CTD survey was a complete success, due largely to the skill and patience of the officers and crew of R/V OCEANUS. Their efforts in this regard are gratefully acknowledged.

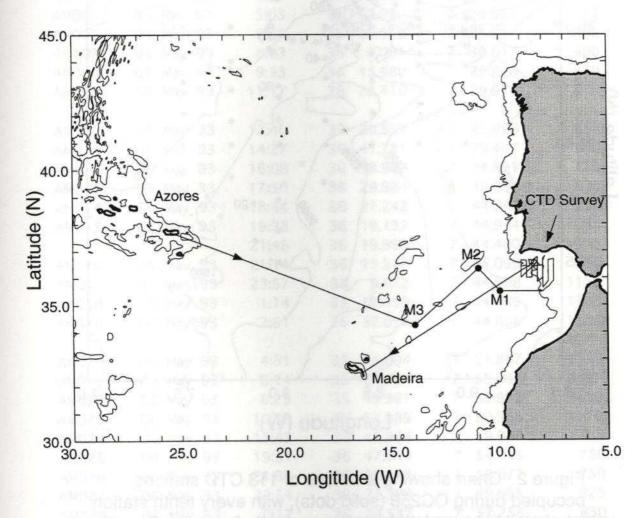


Figure 1. Chart showing cruise track for OC258 (30 April - 14 May 1993). Locations of three sound source moorings are shown by solid dots (M1, M2 and M3). Coastline (land masses are shaded) and 2000 meter isobath are also shown.

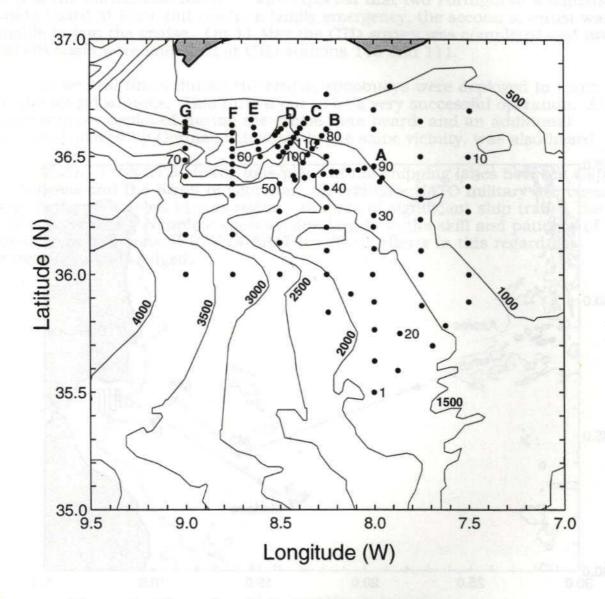


Figure 2. Chart showing locations of 113 CTD stations occupied during OC258 (solid dots), with every tenth station labeled. High-resolution sections are labeled A-G. Coastline (shaded area at top) and bathymetry at 500 meter intervals are also shown.

Table 1: AMUSE Cruise CTD Station Information

Station number			Time UTC	l atitude N			nii Nu	Longitude W	Depth (m)
AM001	04	May 93	21:55		35	29.970	8	0.040	1660
AM002	04	May 93			35	35.560	7		1500
AM003	05	May 93			35	41.865	7		1470
AM004	05	May 93			35	46.960	7		
AM005	05	May 93			35	52.990	7		1290
AM006	05	May 93			35	59.949	7		1215
AM007	05	May 93			36	8.001	7		980
AM008	05	The contract of the contract o			36	15.980	7		850
AM009		May 93			36	22.410	7		825
AM010	05	May 93	12:40		36	29.937	7	29.968	685
AM011	05	May 93	14:27		36	41.731	7	29.467	580
AM012	05	May 93	16:08		36	38.987	7	44.991	775
AM013	05	May 93	17:30		36	29.984	7	45.058	635
AM014	05	May 93	18:44		36	21.242	7	44.968	750
AM015	05	May 93	19:38		36	19.137	7	44.964	1095
		156.03	21:46		36	18.990	7	44.480	1080
AM016	05	May 93	21:14		36	13.977	7	45.099	960
AM017	05	May 93	23:57		36	6.032	7	44.968	1150
AM018	06	May 93	1:14		35	59.950	7	44.995	1305
AM019	06	May 93	2:51		35	52.034	7	44.856	1435
AM020	06	May 93	4:31		35	45.004	7	51.867	1650
AM021	06	May 93	6:14		35	37.964	7	59.932	1627
AM022	06	May 93	8:25		35	45.961	5 7	59.932	1650
AM023	06	May 93	10:32		35	52.989	9 7	59.969	1770
AM024	06	May 9	15:43		36	41.963	5 7	59.947	730
AM025	06	May 9	3 19:51		36	47.944	7	54.715	750
AM026	06	May 93	3 21:35		36	36.978	7	59.877	750
AM027	06	May 9:	3 22:54		36	27.389	7	59.955	825
AM028	07	May 9	0:17		36	24.537	7	7 57.256	830
AM029	07	May 9	1:01		36	23.567	- 7	7 58.046	1050
			0		36	20.096		3 2.780	
AM030		May 9			36			7 59.967	1240
AM031	07	May 9	5:43		36	12.083		0.118	1500
AM032	07	May 9	7:10		36	6.514	8	7 59.913	1700
AM033	07	May 9	8:46		36	0.000		0.400	1500

Table 1 (cont'd): AMUSE Cruise CTD Station Information

Station number	Date		Time UTC		Latitude N		L	ongitude W	Depth (m)	
AM034	07	May	93	10:25		35	55.000	8	7.500	1965
AM035		May		12:41		35	50.352	8	14.550	2150
AM036	07	100 S 200 M		14:24		36	0.020	8	15.033	2050
AM037	07	South Profession		15:46		36	6.037	8	14.943	1970
AM038	07			17:12		36	11.953	8	15.019	1400
AM039	07	May	93	18:28		36	17.017	8	15.038	1710
AM040	07	May	93	19:46		36	22.011	8	14.989	1240
AM041	07	May	93	21:14		36	30.018	8	14.980	1325
AM042	07	May	93	22:35		36	36.997	8	14.968	810
AM043	08	May	93	0:07		36	45.896	8	14.963	650
AM044	80	May	93	1:48	4	36	38.205	8	28.033	900
						36	37.800	8	28.734	1030
AM045	08	May	93	3:16		36	37.026	8	29.409	1195
AM046	08	May	93	4:16		36	36.263	8	30.440	1695
AM047	80	May	93	6:32		36	35.426	8	31.337	2002
AM048	80	May	93	7:02		36	32.500	8	30.480	2190
AM049	80	May	93	8:16		36	29.993	8	29.936	2280
AM050	08	May	93	9:59		36	23.016	8	29.960	2410
AM051	80	May	93	11:39		36	15.975	8	30.009	1800
AM052	08	May	93	13:14		36	7.979	8	30.003	1785
AM053	08	May	93	14:48		36	0.021	8	29.990	2570
AM054	80	May	93	16:50		35	59.948	8	44.962	3250
AM055	80	May	93	18:39		36	10.060	8	44.990	2775
AM056	08	May	93	20:26		36	20.033	8	44.970	3000
AM057	08	May	93	21:51		36	26.048	8	45.017	2325
AM058	08	May	93	23:00		36	22.943	8	45.025	2825
AM059	09	May	93	0:21		36	27.972	8	44.961	1620
AM060	09	May	93	1:38		36	29.975	8	45.002	1350
AM061	09	May	93	2:43		36	31.935	8	44.967	1260
AM062	09	May	93	3:49		36	33.964	8	45.059	1035
AM063	09	May	93	4:48		36	36.014	8	45.023	965
AM064	09	May	93	5:48		36	37.942	8	45.061	840
AM065	09	May	93	7:47		36	37.960	9	0.051	1190
AM066	09	May	93	8:43		36	38.786	9	0.010	870
AM067	09	May	93	9:26		36	37.180	8	59.881	1405
AM068	09	May	93	10:27		36	36.142	8	59.993	1725

Table 1 (cont'd): AMUSE Cruise CTD Station Information

	tation umber	Date			Time UTC	Lat	Latitude N		Longitude W	Depth (m)
	AM069	09	May	93	11:54	36	32.034	8	59.977	2130
VŠ	AMOZO	00	May	02	12.04	20	20.004	0	0.010	1500
	AM070		May		13:04	36	28.994	9	0.010	1500
	AM071		May		14:15	36	24.948	8	59.920	2250
	AM072		May		15:32	36	20.002	8	59.988	3220
	AM073		May		17:23	36	10.013	8	59.970	3400
	AM074		May		19:03	35	59.994	8	59.968	3680
	AM075		May		23:33	36	28.440	8	22.472	1570
	AM076		May		0:48	36	24.988	8	25.540	1800
	AM077		May		2:18	36	30.490	8	20.937	1725
	AM078		May		3:20	36	31.977	8	19.499	1500
,	AM079	10	May	93	4:21	36	33.546	8	17.943	1200
	AM080	10	May	93	5:18	36	35.284	8	16.424	500
	AM081		May		6:14	36	36.894	8	14.897	855
	AM082		May		8:05	36	24.034	8	25.050	1800
	AM083		May		9:13	36	24.551	8	21.997	1260
	AM084		May		10:12	36	25.130	8	19.194	1150
	AM085		May		11:06	36	25.492	8	15.930	1120
	AM086		May		12:12	36	26.036	8	11.885	1090
	AM087		May		13:03	36	26.050	8	13.380	1130
	AM088		May		14:27	36	26.579	8	5.012	1210
	AM089		May		15:26	36	27.020	8	2.913	1100
	AM090	10	May	93	16:16	36	27.536	7	59.897	810
	AM091		May		17:25	36	26.472	8	7.976	1165
	AM092		May		19:43	36	39.681	8	21.032	730
	AM093		May		20:56	36	38.457	8	22.226	830
	AM094		May		21:37	36	37.184	8	23.505	1000
	AM095		May		22:56	36	35.951	8	24.499	1230
	AM096	11	The state of the state of		0:08	36	34.789	8		1230
	AM097	11	30		1:04	36	33.455	8	26.515	1630
	AM098	11			2:10	36	32.391	8		1820
	AM099		May		3:23	36	31.169	8	28.789	2045
	AM100	11	May	93	4:34	36	30.042	8	29.947	2290
	AM101	11			6:15	36	29.922	8		2420
	AM102		May		7:22	36	31.798	8		1860
	AM103		May		8:29	36	33.803	8		1570

Table 1 (cont'd): AMUSE Cruise CTD Station Information

Station	Date	Time UTC	atitude N	Longitude W	Depth (m)	
AM104	11 May 93	9:46 3	6 35.543	8 37.836	1130	
AM105	11 May 93	10:52 3		8 38.160	860	
AM106	11 May 93	11:49 3		8 38.992	750	
AM107	11 May 93	13:39 3		8 23.376	1040	
AM108	11 May 93	14:48 3		8 24.360	1060	
AM109	11 May 93	15:42 3		8 25.400	1208	
AM110	11 May 93	16:37		8 26.447	1600	
AM111	11 May 93	17:49 3		8 27.581	1800	
AM112	11 May 93	19:16 3		8 28.741	2090	
AM113	11 May 93	20:23 3		8 30.074	2250	
	s Body ed				SECRET	
		170				
	JET #568 21 KT					
	1,503,41,12					

Section 2: Methods

A. CTD Data Collection and Processing

The CTD used during this cruise was borrowed from the SeaSoar group at Woods Hole Oceanographic Institution (WHOI). It is a Sea-Bird Model 911 with redundant sensors for temperature and conductivity. An oxygen sensor was attached but samples were not taken for oxygen analysis and oxygen data were ignored. At each station, the CTD and rosette, with two Niskin bottles, were lowered to within 10 meters of the sea floor or 2000 meters, whichever was deeper. Water samples were generally taken for salinity calibration at the bottom or in isohaline layers. The data were logged at 24 Hz on a shipboard PC.

Basic processing was done on the ship using the Sea-Bird software package. Based on the good match between temperature sensors, and the small mean difference between sensor-derived and water sample salinity (~0.006 PSU), no calibration corrections were made to either temperature or salinity. Altogether, 113 CTD stations were occupied ranging in depth from 500 to 2000 meters. These included three short tow-yo stations (stations 15, 29 and 44).

Data processing continued back at WHOI, where Julie Pallant removed bad data points not identified during shipboard processing. The same parameters were used to reprocess the data, which were averaged in 2 decibar bins and stored in ASCII format.

As part of the CTD processing, tests were done to check alignment of temperature and conductivity records for the AMUSE CTD data set. Basically the correlation function was computed between temperature and conductivity using the MATLAB routine "xcov(t,c,'coeff')." When the whole record was used, the function was dominated by the low-frequency signal, and the function was not useful for determining lags on the order of one to three scans. The records were then broken up into 100-scan pieces, the correlation function was computed for each piece and the average of all pieces was estimated.

Results showed the highest correlation occurred at zero time lag for both the raw data and the data that had been aligned by one scan (conductivity moved ahead one scan). The shapes of the functions were different, and the correlation at zero lag was just slightly higher for the one-scan lagged data.

We concluded that either a no lag or one-scan lag was sufficient. Since the data had already been processed with the one-scan lag, no reprocessing was done. The CTD data are presented in this report in plot form: vertical profiles of potential temperature, salinity and density (sigma -1) at each station are shown in Appendix A; T/S plots for each station are shown in Appendix B; and vertical sections of potential temperature, salinity and sigma-1 are shown in Appendix C.

B. RAFOS floats

Toward the end of the cruise, a tentative site was chosen for the sequential float deployments that would take place over the next six months, and two RAFOS floats (made by SeaScan, Inc.) were launched near that site to test the acoustic tracking system. Table 2 contains the launch and surface information for these two floats. One of them, AM113, sank below the target pressure (1100 dbars) and terminated its mission prematurely. No useful data was obtained from this float. Figures 3 and 4 show the trajectory and temperature and pressure records, respectively, for AM101. This float successfully completed a 30-day mission, collecting acoustic tracking, temperature and pressure data at 8-hour intervals.

Table 2: RAFOS float launch and surface information.

Float #		(yymmdd)	Launch (N)	Site (W)	Surface Date	Surfac (N)	e Site (W)	Days
101	110	930511	36 33.36	8 26.28	930610	37 41.52	10 3.84	30
113	111	930511	36 32.16	8 27.48	930512	36 31.98	8 26.82	1

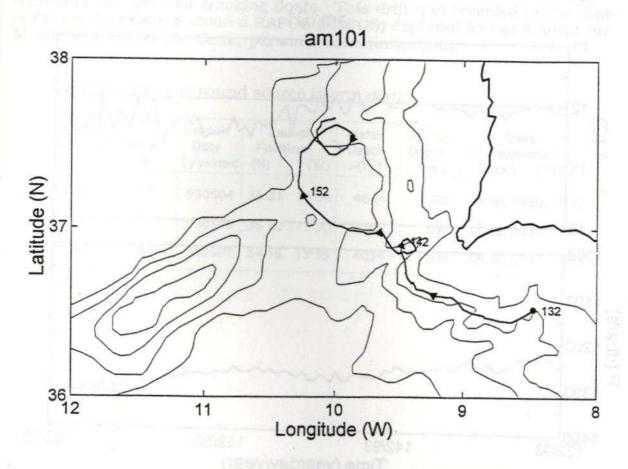


Figure 3. Track of RAFOS float AM101. The track connects position of the float at 8-hour intervals and positions are marked with an arrow every five days. Numbers along the track are dates in yeardays, 1993. The coast of Portugal is also shown with bathymetric contours every 1000 meters.

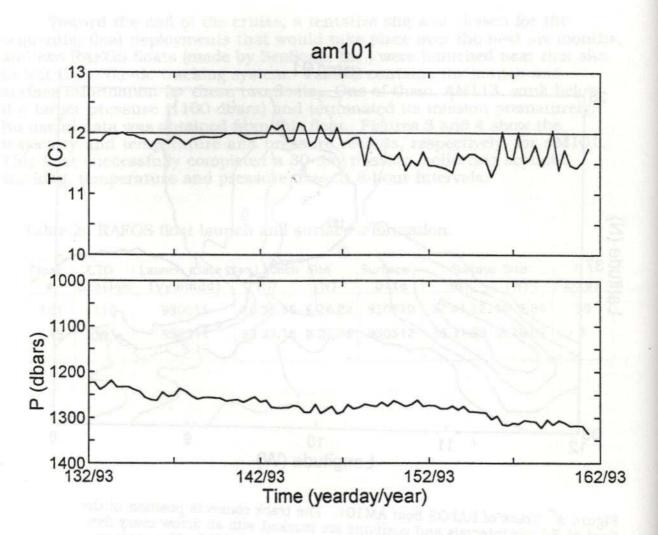


Figure 4. Time series of temperature (upper panel) and pressure (lower panel) along the track of RAFOS float AM101.

C. Acoustic Sound Sources

Three acoustic sound sources, manufactured by Webb Research Corporation, were moored at the sites listed in Table 3 and shown in Figure 1. The sources were suspended in the water column at a depth of 1500 meters (nominal) and programmed to transmit three times per day. Their nominal life expectancy is 3.5 years. They were deployed without acoustic releases since there were no plans to recover the moorings.

During the fall of 1993, the clock in M3 started to drift and it was thereafter not used for tracking floats. This drift was revealed in the time-of-arrival data from a moored RAFOS (MAFOS) deployed by the Institut fur Meereskunde-Kiel (W. Zenk, personal communication).

Table 3: Acoustic sound source information.

Mooring S	Serial	Launch Date	Lau Positi	nch on	Water Depth	Source Depth	Daily Transmission
	#	(yymmd	(N)	(W)	(m)	(m)	Times (UTC)
М1	72	930504	35 31	10 00	4644	1500	0030, 0830, 1630
M2	73	930503	36 20	11 00	4605	1500	0130, 0930, 1730
М3	80	930502	34 16	13 59	4036	1500	0132, 0932, 1732

Section 3: Acknowledgements

The AMUSE project was funded by the National Science Foundation through Grant No. OCE-91-01033 to Woods Hole Oceanographic Institution, Grant No. OCE-91-00724 to Scripps Institution of Oceanography and by the Luso-American Foundation for Development (FLAD) through Grant No. 54/93 to the University of Lisbon. On behalf of the science party of R/V OCEANUS Voyage 258, Leg II, we wish to express our sincere thanks and appreciation to Captain Paul Howland and the crew of R/V OCEANUS, and we are grateful for the support and cooperation we received from the Government of Portugal. We also gratefully acknowledge the students and staff from the Oceanography Group of the University of Lisbon for their participation on the cruise. The CTD used on the cruise was loaned to us by Jim Luyten and the WHOI SeaSoar group. Without their support, this survey would not have been possible.

Section 4: References

Rossby, T., D. Dorson and J. Fontaine, 1986. The RAFOS System. Journal of Atmospheric and Oceanic Technology, 3: 672-679.