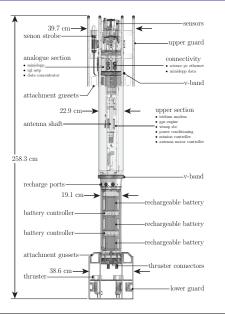
- ASIP is an autonomous vertically-moving profiling platform that is equipped with a suite of senors that make measurements of the physical properties of the ocean from a maximum depth of 100m up to the air-sea interface.
- ASIP is equipped to measure pressure, temperature, conductivity, shear, noise, photosynthetically active radiation (PAR), oxygen concentration and saturation, and fluorescence.
- ASIP is ~2.5m in length and weighs approximately 100kg. The sensors are located at the top of ASIP and are protected by a guard.

# ASIP Description



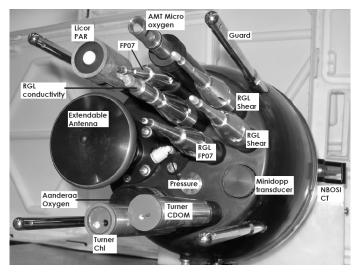
- Profiling is accomplished with three thrusters that submerges the positively buoyant instrument to a maximum depth of 100 m.
- Once the pre-programmed depth is reached, the thrusters turn off and ASIP ascends to the surface at about 0.5 ms<sup>-1</sup> acquiring data along this path.
- Once the surface is reached, ASIP gets its location with the GPS engine and transmits this with the iridium modem.

# ASIP Description



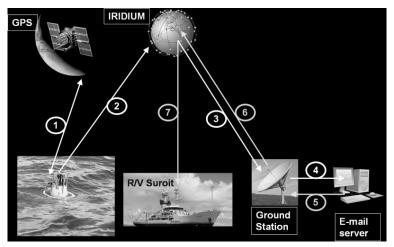
- ASIP is strapped to the deck to test the satellite communications
- Antenna extends to get it high enough to connect with the satellite

#### **ASIP** Sensors



A new hydrophone will be attached to quantify breaking waves and bubbles

### ASIP Communications



Two way communication with ASIP is provided by iridium

- ASIP is first lifted into the small boat (RHIB) along with the driver, crew member and two scientists
- The boat is launched and ASIP is lifted over the side
- The sensor cover is removed and a magnet is used to start the mission
- ASIP is then left in the water and the RHIB returns to the ship

# ASIP Deployment



ASIP is lifted into the RHIB with an officer, crew member, and two scientists

# ASIP Deployment



ASIP is lifted over the side of the RHIB and the sensor cover is removed before release

Brian Ward ASIP during the BOWave Cruise

# ASIP Deployment



ASIP begins to profile soon after being released from the RHIB

Brian Ward ASIP during the BOWave Cruise

- Waiting for ASIP to submerge after a profile: http://www.youtube.com/watch?v=emxKl5beQkg
- Deploying ASIP from the RHIB: http://www.youtube.com/watch?v=3oxXLD5nJBk
- Returning to ship after an ASIP deployment: http://www.youtube.com/watch?v=03QzI2xe5pM

- ASIP will provide periodic updates on its location via iridium SBD
- ASIP's mission can be stopped at any time by sending it the abort command
- This will put ASIP into a mode where it will remain at the surface and relay its position every 2 minutes
- The ship will move to the location of ASIP and the RHIB will be launched and ASIP recovered

- After recovery, the batteries on ASIP need to be recharged
- This will require space in a dry environment, as the instrument need to be partially opened for battery recharging
- ASIP can sit in a cradle on the floor during the recharge
- About 2m of bench space are required for the ancillary equipment